

What shape is a circle?

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How do we define a circle? ←

We usually define a circle as

$$C = \{\vec{x} \mid \|\vec{x}\| = 1\}$$

(i.e., the set of all vectors \vec{x} of length 1).

Of course, we need to make sense of $\|\vec{x}\|$, the length of a vector.

Most people start with the definition

$$\|\vec{x}\| = \left(\sum_i x_i^2 \right)^{\frac{1}{2}},$$

but since we are mathematicians, and don't like our definitions to be too special, we can generalize:

$$\|\vec{x}\|_p = \left(\sum_i |x_i|^p \right)^{\frac{1}{p}}.$$

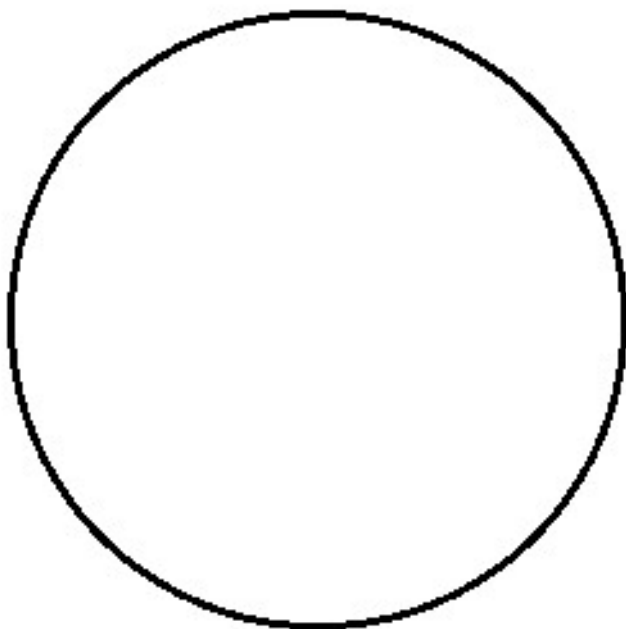
for $p > 0$.

We then have the more general definition of the p circle (in dimension n):

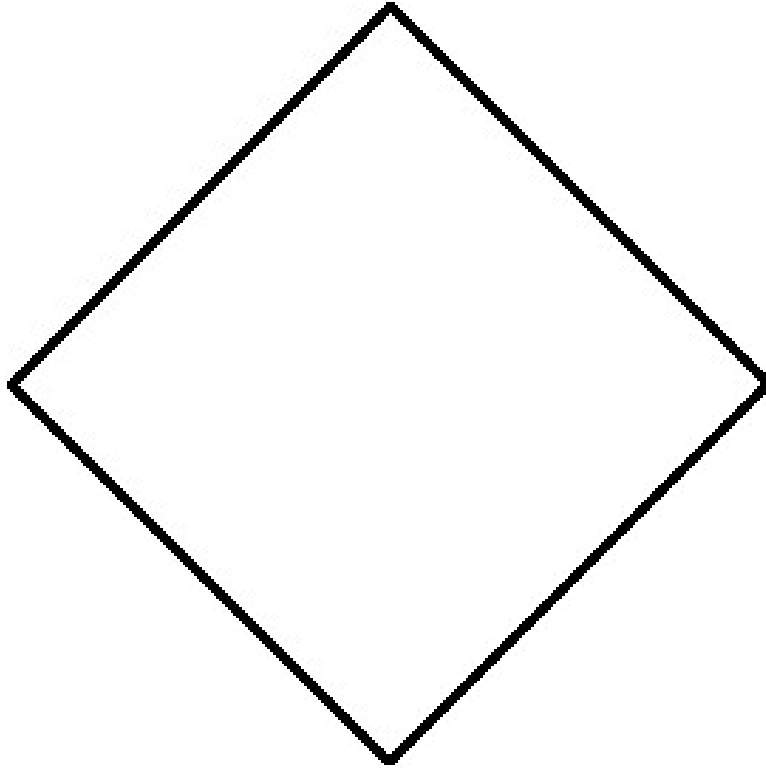
$$C_p^n = \{\vec{x} \mid \|\vec{x}\|_p = 1\}.$$

What does C_p^n look like? Let's work in two dimensions, and leave out the dimension label.

C_2 is the familiar circle:



C_1 is a diamond:



Note that if our vector space is over $\{0, 1\}$, then a vector is just a string of zeros and ones, and $\|\vec{x}\|_1$ is just the number of ones in the string.

We can convert our length measures into a distance measures:

$$d_p(\vec{x}, \vec{y}) = \|\vec{x} - \vec{y}\|_p = \left(\sum_i |x_i - y_i|^p \right)^{\frac{1}{p}}.$$

In particular, if our vector space is over $\{0, 1\}$, then $d_1(\vec{x}, \vec{y})$ is just the Hamming distance between the two vectors (i.e., the number of places in which the two strings differ).

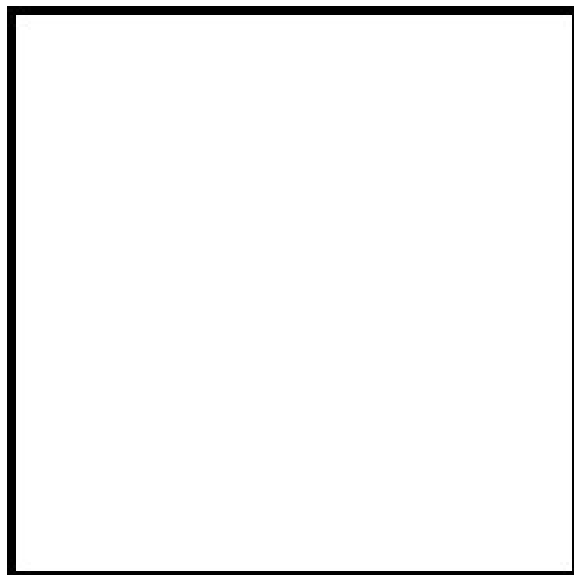
We can also define

$$\|\vec{x}\|_\infty = \lim_{p \rightarrow \infty} (\|\vec{x}\|_p).$$

Going through the math, we have that

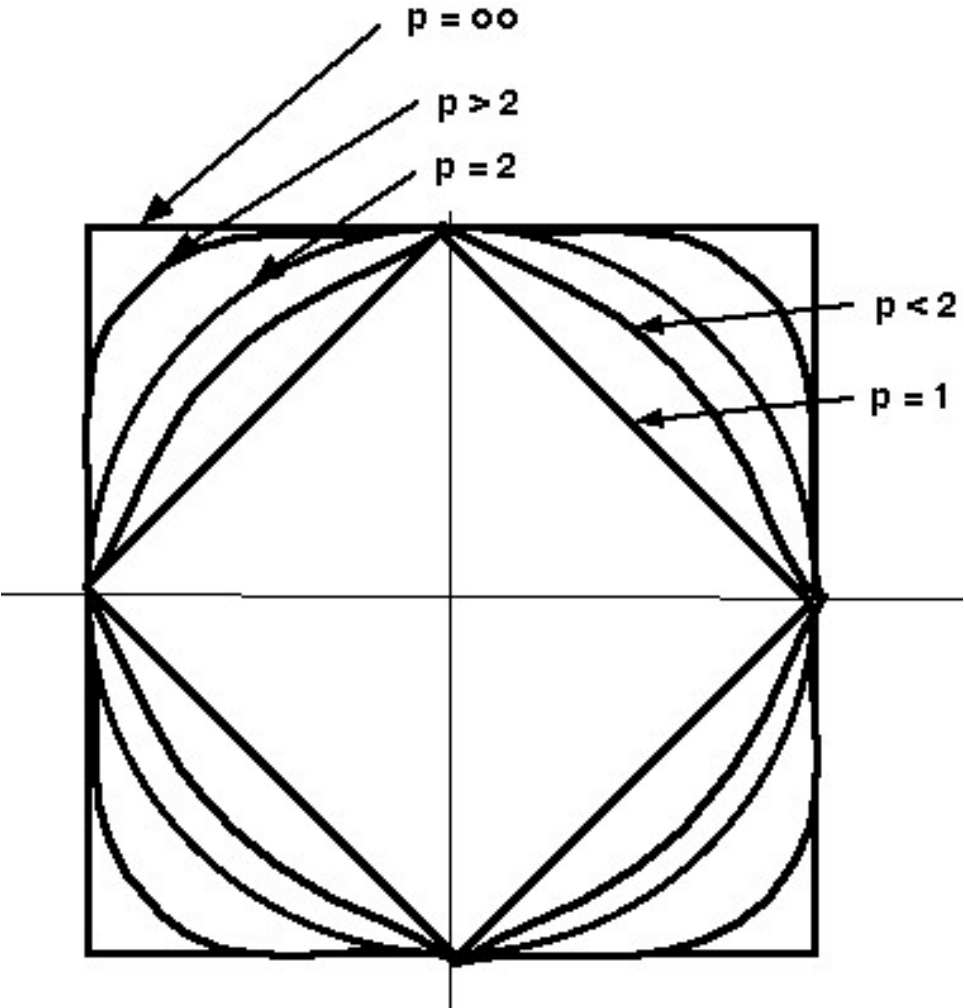
$$\|\vec{x}\|_\infty = \max_i (|x_i|).$$

We then have that C_∞ is a square:



This means that for a mathematician, a circle is a circle, is a diamond, is a square (which may explain why I always had trouble with those “shape matching” tests ... :-)

In general, we have the following sort of picture of various circles:



Homework exercises:

What happens for $0 < p < 1$?

What happens if we take the limit as p goes to 0?